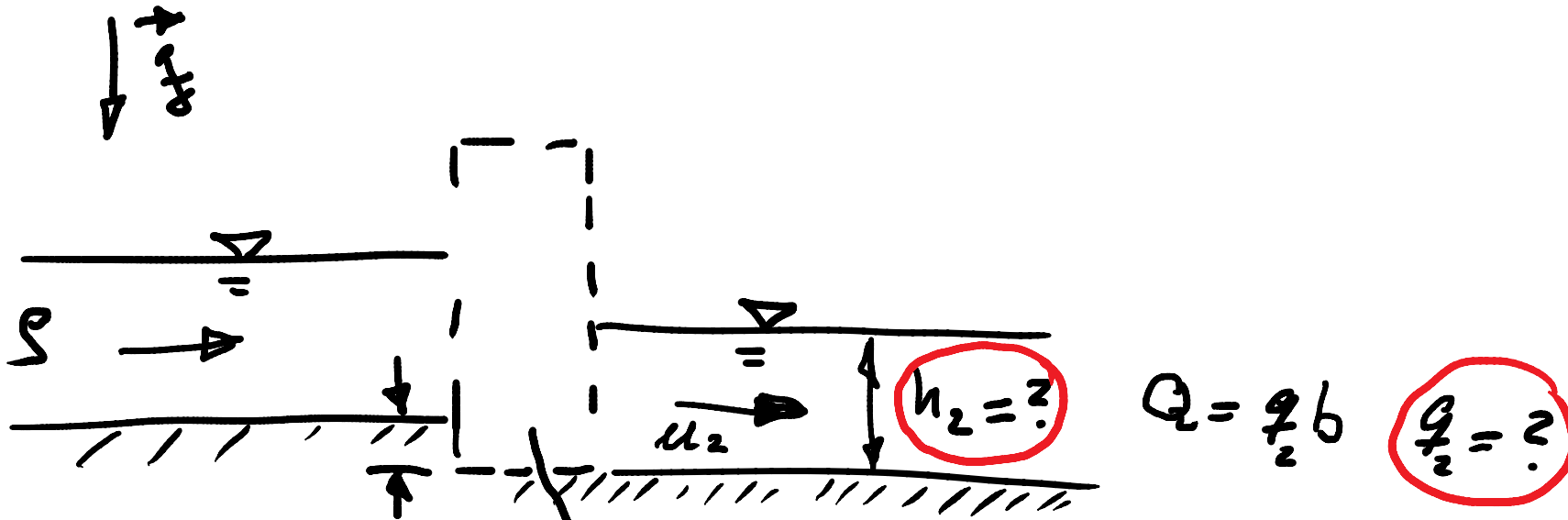


Optimierung des Betriebsverhaltens einer Wasserleitung in einem Sinne.



Small h_2 and
small Q_2 value.

$P_{Tmax} = ?$:

$$\left. \begin{aligned} \frac{\partial P_T}{\partial h_2} &\stackrel{!}{=} 0 \\ \frac{\partial P_T}{\partial Q_2} &\stackrel{!}{=} 0 \end{aligned} \right\} \begin{aligned} h_{2opt} \\ Q_{2opt} \end{aligned}$$

Q Volumenstrom (\dot{V})

b Gerinnebreite

$q = \frac{Q}{b}$ Volumenstrom pro Breite

$$u = \frac{Q}{bh}$$

q

$$\frac{u}{\sqrt{gh}} = Fr = \frac{q}{g^{1/2} h^{3/2}}$$

h

Wassertiefe.

h

h



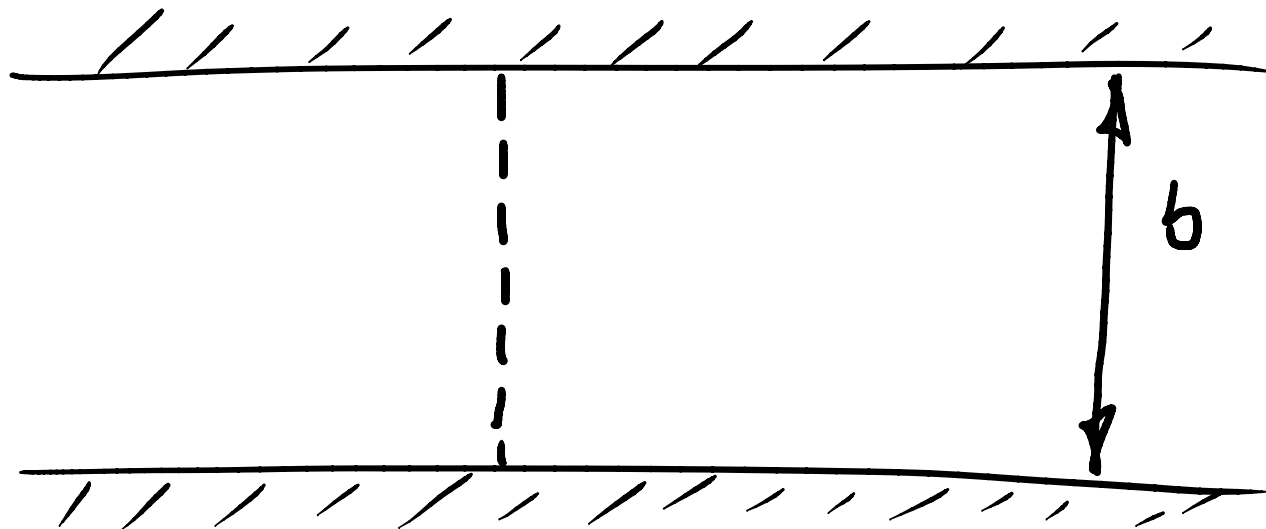
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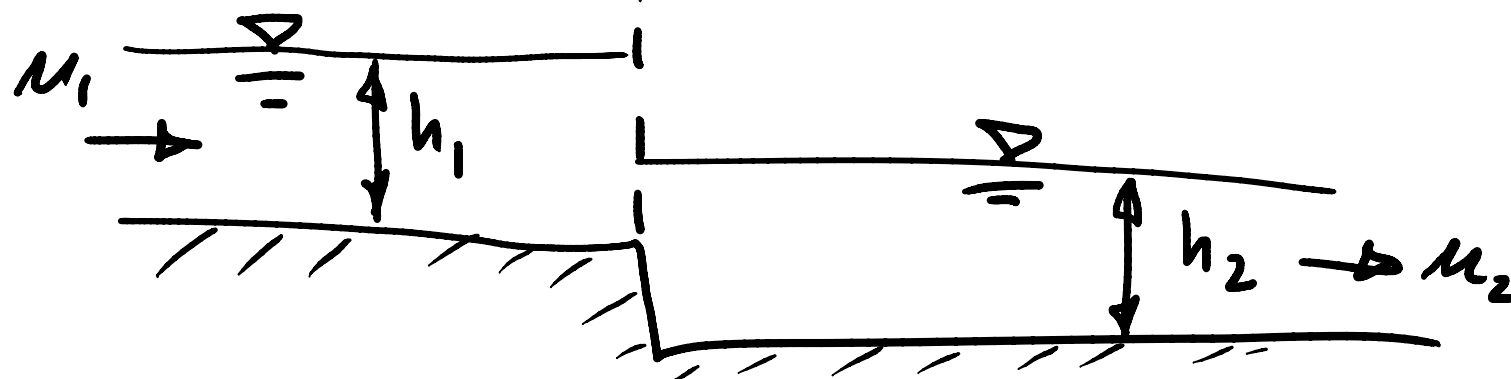


Draufputz mit Maschin.



$h_{10} \neq h_1$

$u_1 \neq u_{10}$



ohne Maschin.



Hier: Wir optimieren unabhängig
von geometrischen Verhältnissen

„ ... dem Anpassen des Umlaufes ... „

fischförmige Turbine mit geometrischer
Anpassung.



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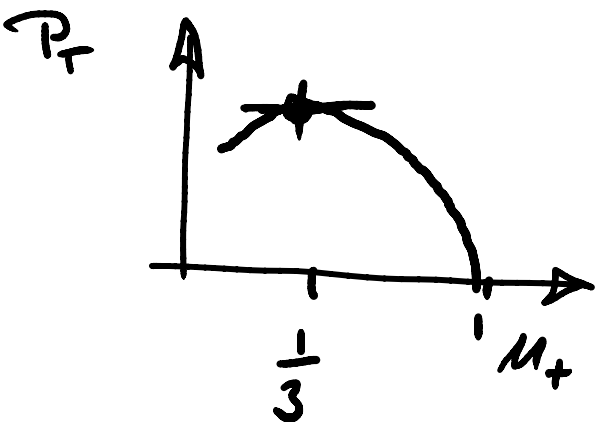
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Wintersemester 2012/13
Vorlesung 7 F 87



Wind

$$\frac{M_2}{M_1} = M_+$$

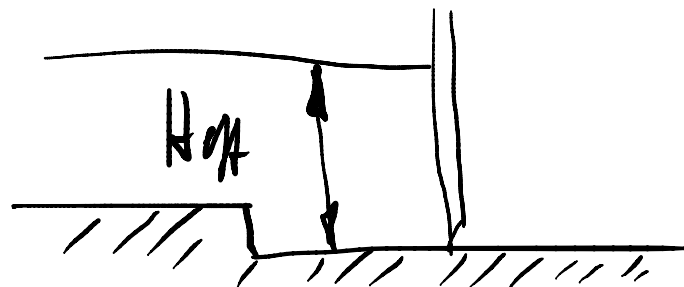
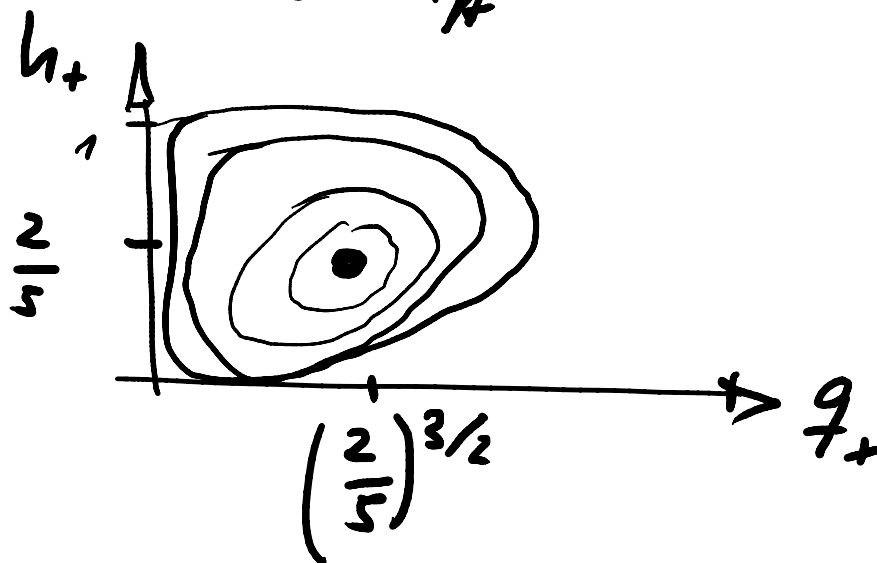


$$P_{\text{avail}} := \frac{\rho}{2} M_1^3 A \left[\rightarrow \right]$$

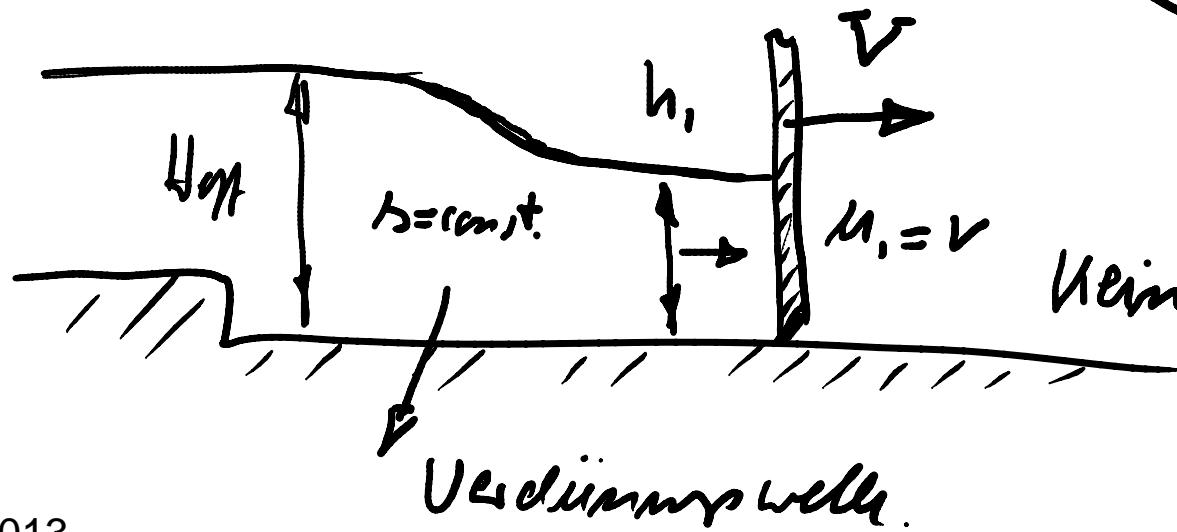
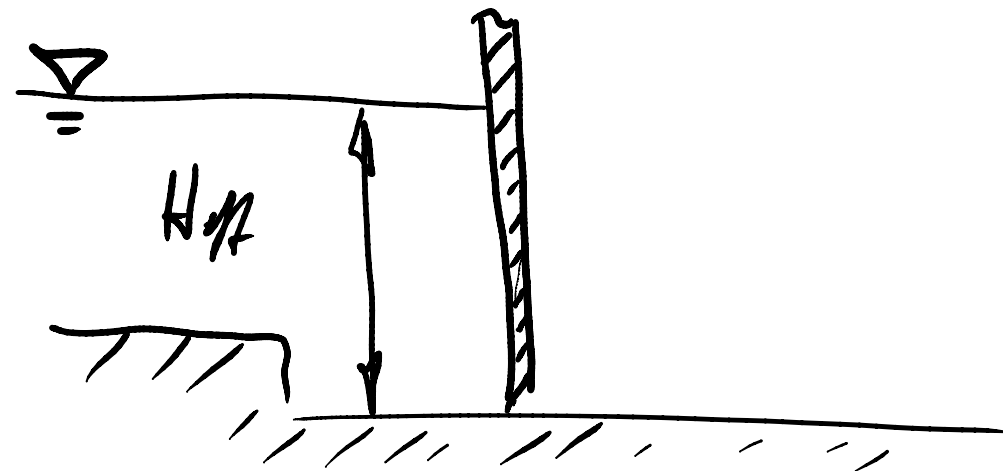
$$C_p := \frac{P_T}{P_{\text{avail}}}$$

klare Wasserlauf

$$q_+ := \frac{q_2}{\rho^{1/2} H_{eff}^{3/2}}, \quad h_+ := \frac{h_2}{H_{eff}}$$



Die ideale Vent & Luftmaschine.

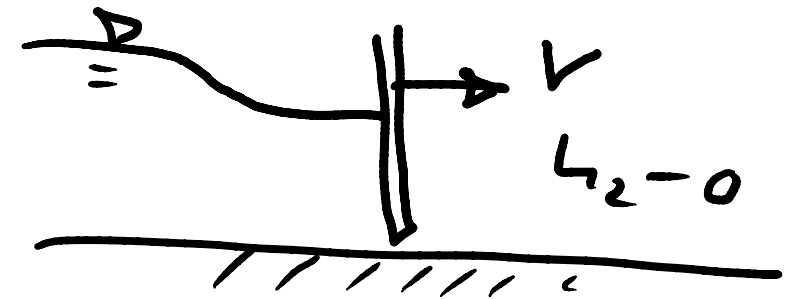


~> Exeje.

Kein Unterwasser.

Wellenleistung für die ideale Wasserkraftmaschine.

$$P_T, h_2=0 = b \int_0^{h_1} \rho g y u_1 dy$$
$$= \frac{1}{2} \rho g h_1^2 u_1 b$$



$$H_{eff} = h_{10} + \frac{u_{10}^2}{2g} = h_1 + \frac{u_1^2}{2g}$$

Stauhöhe.

$$Fr_2 = \frac{u_2}{\sqrt{g h_2}}$$



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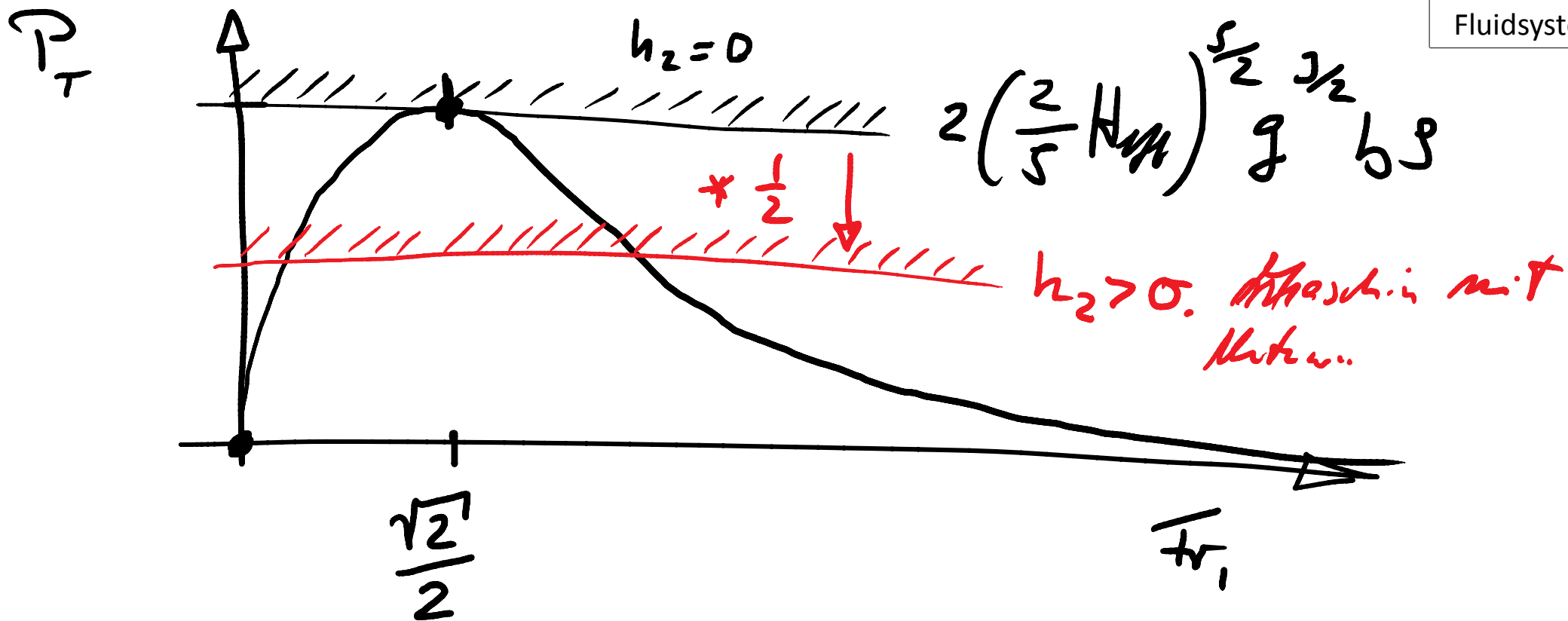


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Skalierung von
Fluidsystemen

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Wintersemester 2012/13
Vorlesung 7 F 90



$$P_T, h_2=0 = \rho b H_{eff}^{\frac{5}{2}} g^{\frac{3}{2}} \frac{2\sqrt{2} Fr_1}{(2 + Fr_1^2)^{\frac{5}{2}}}$$

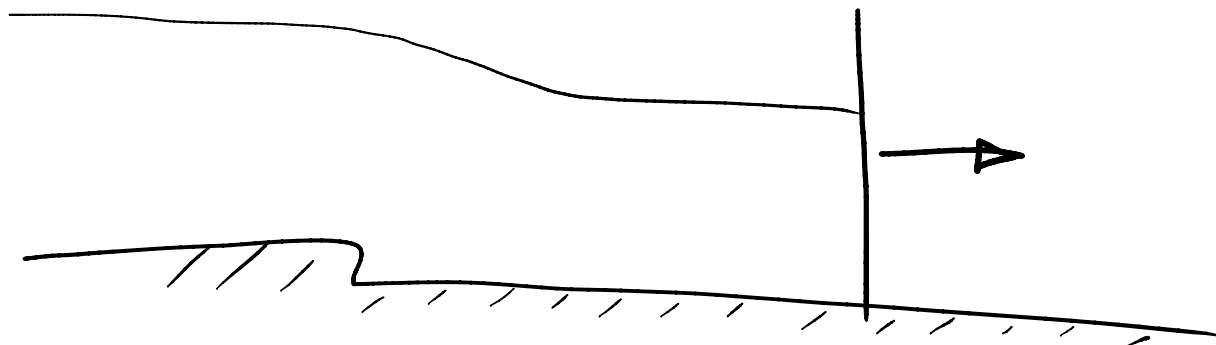


Upper Limit for Hydropower in an Open-Channel Flow

↳ Pelz.

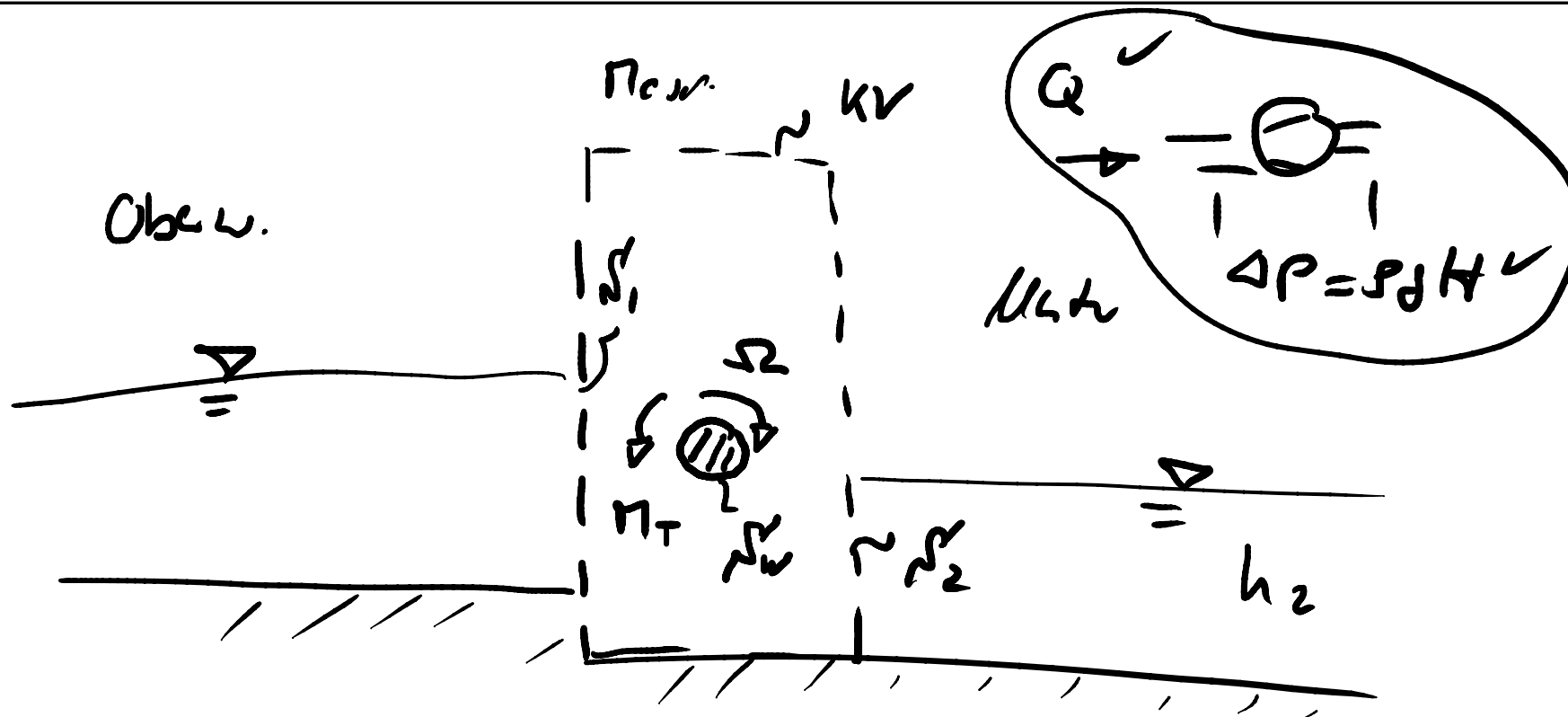


$$C_p = 1$$



$$P_{\text{avail}} := 2 \left(\frac{2}{5} H_{\text{VM}} \right)^{5/2} \rho^{3/2} b^3$$

$$C_p := \frac{P}{P_{\text{avail}}}$$



$$\frac{DK}{Dt} + \frac{DE}{Dt} = \oint_{\partial V} \vec{t} \cdot \vec{n} dS + \int_V \rho \vec{k} \cdot \vec{u} dV - \cancel{\oint_{\partial V} \vec{q} \cdot \vec{n} dS}$$

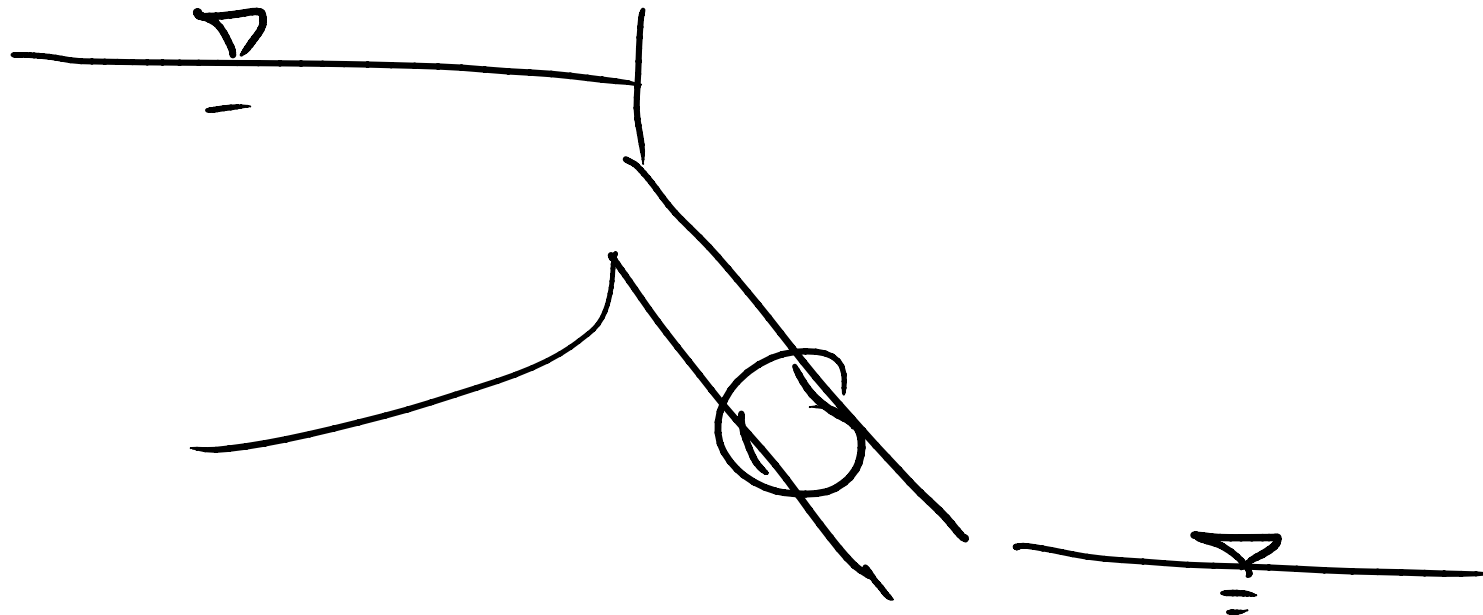
$$\frac{D}{Dt} \int_{V(t)} \rho \left(\frac{u^2}{2} + e \right) dV = \dots$$



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Optimierung und
Skalierung von
Fluidsystemen

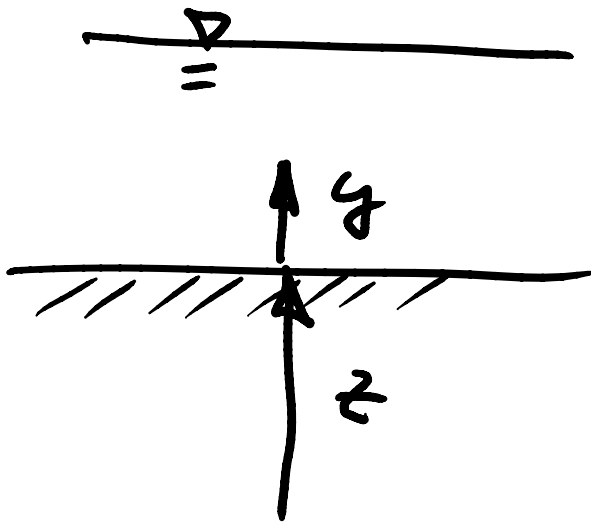


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Wintersemester 2012/13
Vorlesung 7 F 94



- Im zeitlich Mittel stationäre Zustände.

- \vec{g} hat ein Potential. $\psi = g(z+y)$



$$-\rho \vec{n} = -(h-y) \rho g \vec{h}$$

$$+ \int_{S_1 + S_2} \vec{\tau} \cdot \vec{n} dS$$

$$\rho Q \left(\frac{u_2^2}{2} - \frac{u_1^2}{2} \right) + \rho Q (e_2 - e_1) = \underbrace{\int_{S_{\text{voll}}} \vec{\tau} \cdot \vec{n} dS}_{-\dot{D}_T} + \int_V \rho \vec{g} \cdot \vec{u} dV +$$



$$\rho Q \left(\frac{u_2^2}{2} - \frac{u_1^2}{2} \right) + \rho Q (e_2 - e_1) = -\dot{P}_T - \int_{\mathcal{N}_1 + \mathcal{S}_2} \rho g (h - z) u \, d\mathcal{N} +$$

$$\psi = f(z + \frac{u^2}{2g})$$

$\mathcal{N}_1 + \mathcal{S}_2$

$$+ \oint_{\mathcal{S}_2} -\rho \psi \vec{u} \cdot \vec{n} \, d\mathcal{N} + \int_V \rho \psi \nabla \cdot (\rho \vec{u}) \, dV$$

\uparrow Control Surface

$\underbrace{\nabla \cdot (\rho \vec{u})}_{\equiv \sigma} \quad \frac{\partial \rho}{\partial t} = \sigma$

$$\nabla \cdot (\rho \vec{u}) \, dV = \vec{n} \cdot (\rho \vec{u}) \, d\mathcal{N}$$

$$\rho Q \left(\frac{u_2^2}{2} - \frac{u_1^2}{2} \right) + \rho Q (e_2 - e_1) + \rho Q g (h_2 + z_2 - h_1 - z_1) = -\dot{P}_T$$

$$\left(h_1 + \frac{u_1^2}{2g} + z_1 \right) - \left(h_2 + \frac{u_2^2}{2g} + z_2 \right) + \frac{e_1 - e_2}{g} = H_T$$

$\frac{1}{\rho Q g}$

$$H_T := \frac{P_T}{\rho Q g} \quad \text{Stöße über die
Fläche.}$$

$$h_{\text{Loss}} = \frac{e_2 - e_1}{g} = \frac{c}{g} (T_2 - T_1) > 0 \quad \text{Infolge Dissipation.}$$

$$\rho \vec{u} = 0 \quad C_p = C_v = c \quad \text{Wärmekapazität.}$$

$$\boxed{H_1 - H_2 = H_T + h_L} = \frac{H_T}{z}$$

$$H_1 := h_1 + z_1 + \frac{u^2}{2g} \quad \text{totale Höhe.}$$

