

ideale Druckspeich²

Fluidenergietechnik

Arbeitsm.
Kraftm.



FLUID SYSTEM TECHNIK

Technische Fluidsysteme

1. Ventriilm.
trans. rotieren

gesteuert selbsttätig propell. Vent. 4

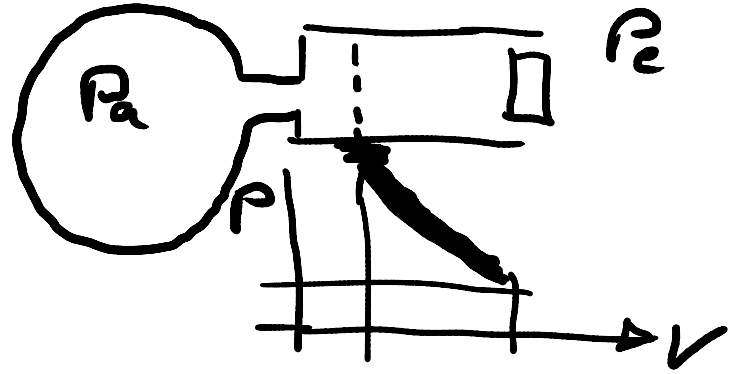
3. plarbo

radial diagon. axial.

Viskositätsm.
z.B. Peristaltik

elektro-dynam.
m.
 $\vec{L} \times \vec{B}$

elektrosom.
Pumpe
 $\vec{S}_c \vec{E}$

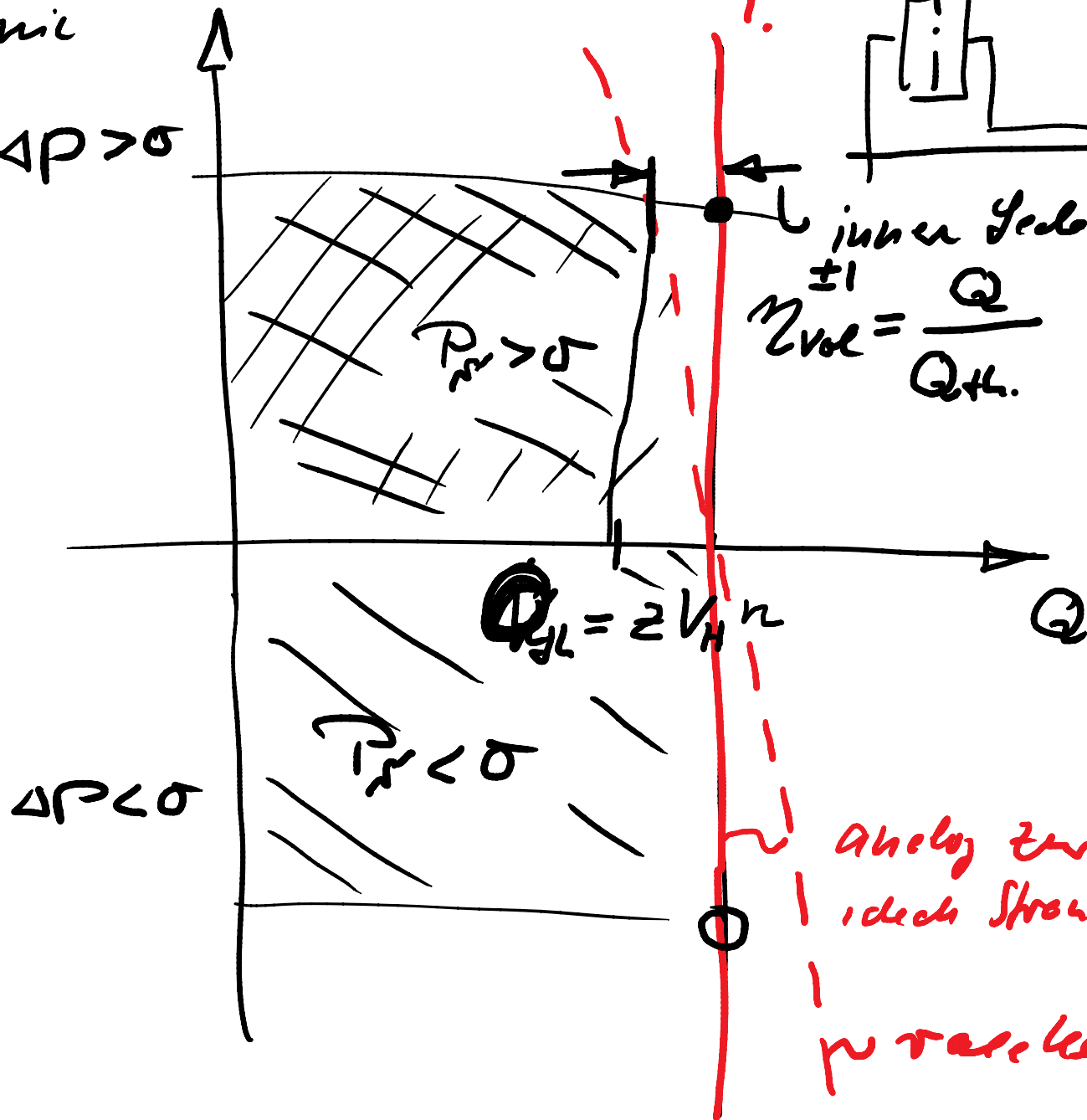




Nennlinie

$\Delta p > 0$

Arbeitsm.
 $P_H > 0$



innerer Gedr.
 $n_{\pm 1} = \frac{Q}{Q_{th}}$

z Zahl der Arbeitsm.

V_H Hubvol

$$n = \frac{1}{T} = \frac{\Omega}{2\pi}$$

Drehz.

Analog zur idealen Strömung.

parallel zur Nennlinie

Werkmaschine
 \Leftrightarrow Motor

$$\zeta_{vol}^{\pm 1} := \frac{Q}{Q_{th}}$$

+1 Arbeiten
-1 Kompression od.
Pumpen.



$$\zeta^{\pm 1} := \frac{\Delta P Q}{M \Omega}$$

$$= \frac{\Delta P V_H^2}{M \pi} \frac{Q}{z V_H^2}$$

ζ_M ζ_{vol}

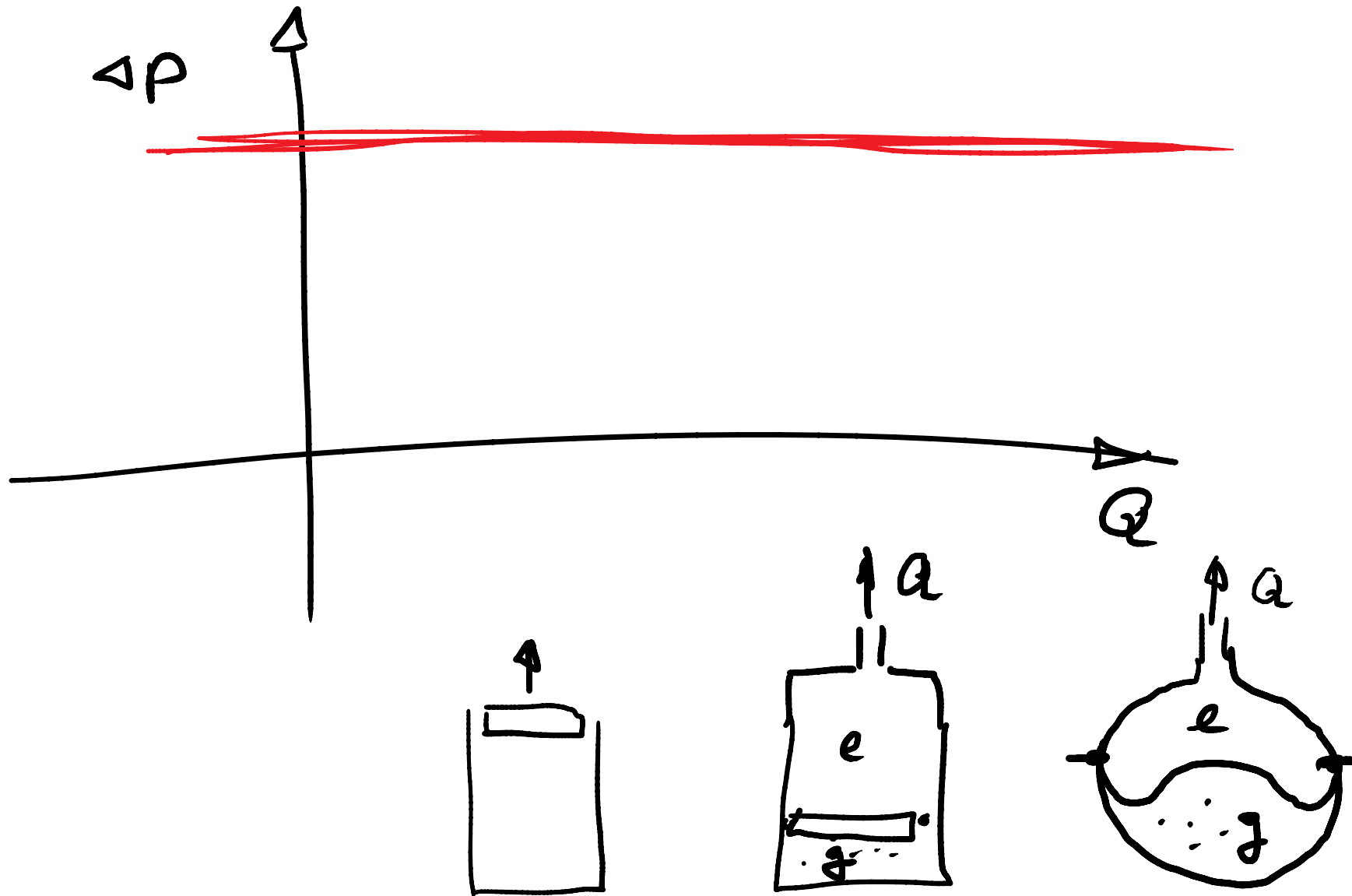
Mechanik
Witbrov

Volumenstrom
Vidgen

$$P_N = \vec{T} \cdot \vec{\Omega} \quad \text{Vollleistung}$$

$$\Delta \hat{=} \text{technische Arbeit / Zeit} \Delta$$

Zu 2. Kennlinie einer idealen Düse



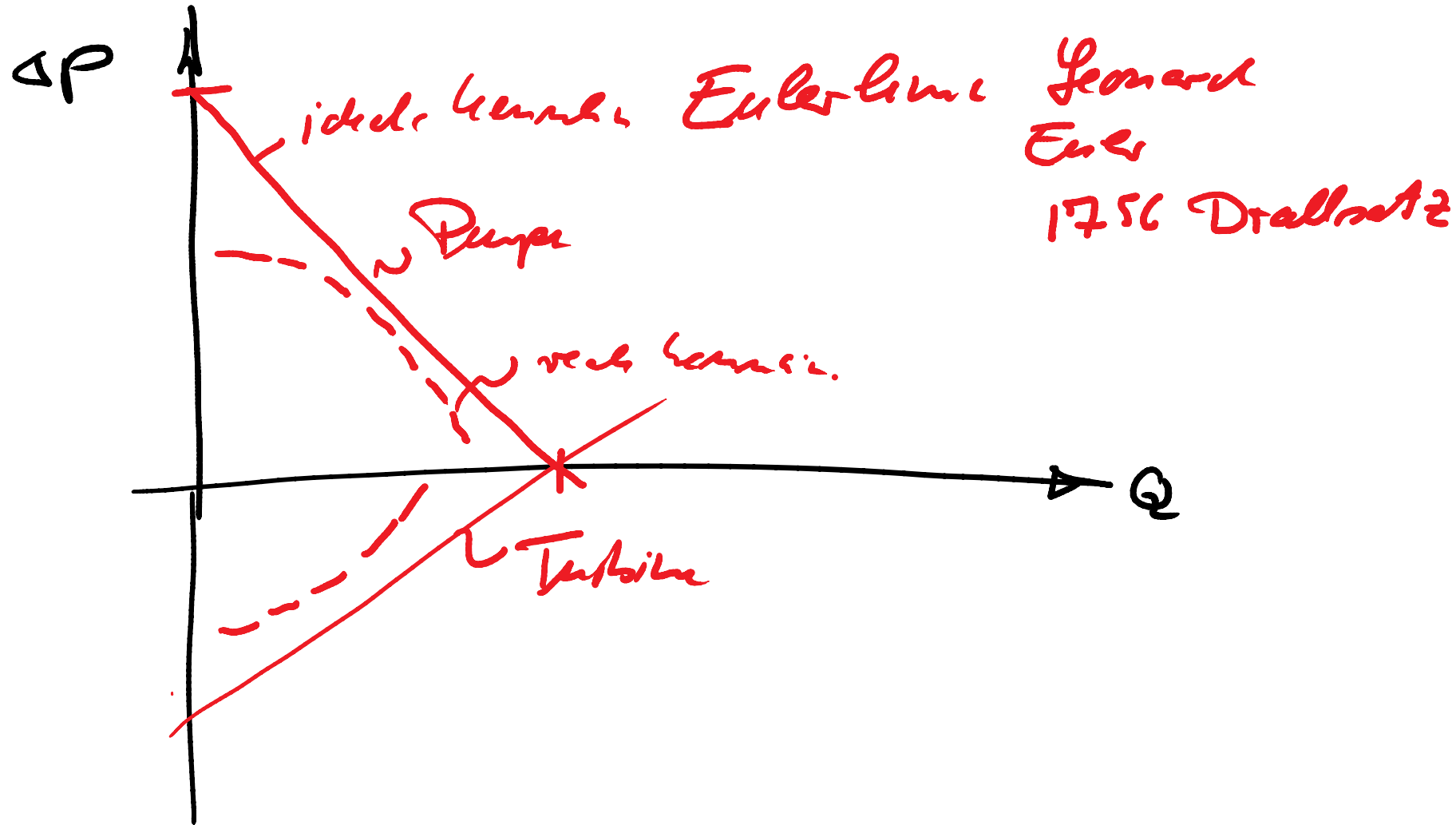
TECHNISCHE
UNIVERSITÄT
DARMSTADT



Technische
Fluidsysteme

Prof. Dr.-Ing. Peter Pelz
Wintersemester 2012/13
Vorlesung 11 F 139

3. Turbomaschine.





1. Erste Hauptsatz (Helmholtz)

$$\dot{m}(h_{t2} - h_{t1}) = \dot{P}_{\text{Zu}} + \dot{Q} \quad \text{für } \frac{\partial \sigma}{\partial t} \equiv 0$$

$M_1 \cdot \Omega = M_2 \cdot \Omega$

$$\dot{m} = \rho Q \quad \text{Parallelstr.$$

$$h_t = \frac{u^2}{2} + \frac{p}{\rho} + \psi + e \quad \text{Absolute v. l. l. m.}$$

$$\dot{Q} \quad \text{Wärmestrom} \equiv \sigma \quad (\text{Nach Seite})$$

2. Dreisatz (z-Komp., $\frac{\partial \sigma}{\partial t} \equiv 0$)

$$\dot{m} (\tau_2 c_{m2} - \tau_1 c_{m1}) = M_2$$



$$(\vec{x} \times \vec{c}) \cdot \vec{e}_z$$
$$= \tau c_u$$

Axialkomponente des
Machungsz. Dralls eines
Flüssigkeitsteilchens.



Wirbelstärke =
Stärke + Potentialwirbel.

- \vec{c} Absolutgeschwindigkeit
- \vec{c}_r Relativgeschwindigkeit
- \vec{c}_u Winkelgeschwindigkeit

$$\vec{c} = c_r \vec{e}_r + c_u \vec{e}_\varphi + c_z \vec{e}_z$$

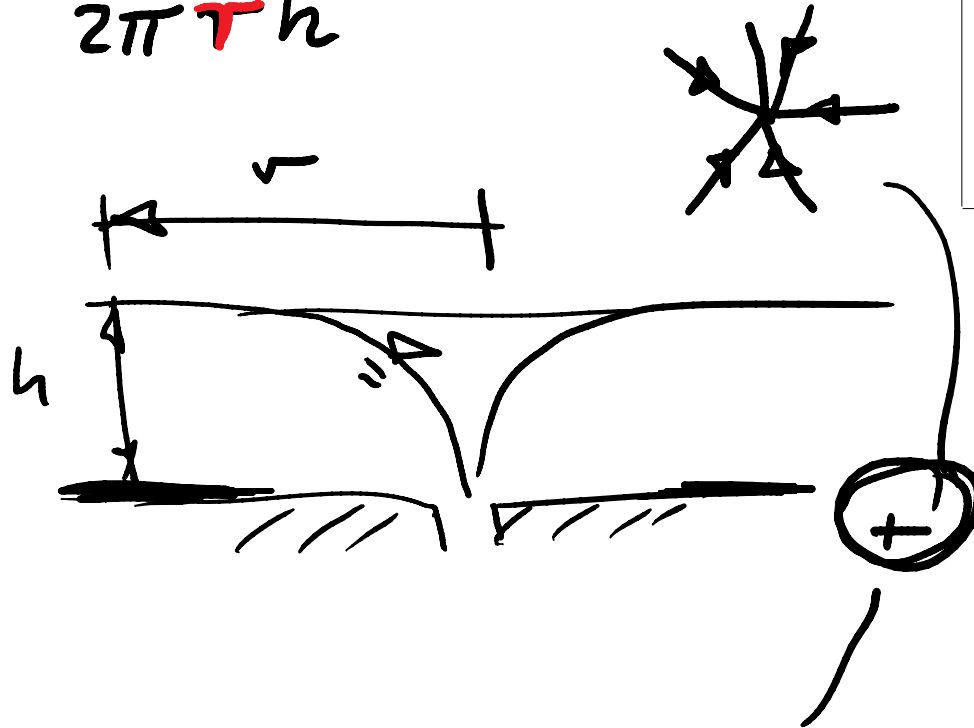
Wirbelsank

$$C_T = -\frac{Q}{2\pi r h}$$

Senk.

$$\vec{C} = -\frac{Q}{2\pi r h} \vec{e}_r + \frac{\Gamma}{2\pi r} \vec{e}_\varphi$$

$$\frac{d\vec{x}}{ds} = \frac{\vec{C}}{|\vec{C}|}$$



TECHNISCHE
UNIVERSITÄT
DARMSTADT



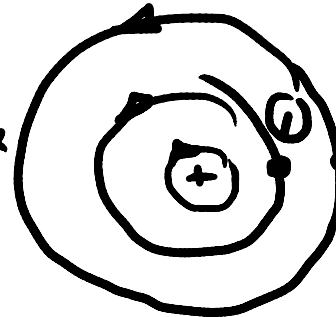
Technische
Fluidsysteme

↳ logarithmisch
Sink.

$$C_u = \frac{\Gamma}{2\pi r}$$

Potentialwirbel

$$C_u r = \frac{\Gamma}{2\pi} = \text{const.}$$



$$m_i (r_2 c_{u2} - r_1 c_{u1}) = P_z$$

$$\Rightarrow r_2 c_{u2} = r_1 c_{u1} \quad 0''$$

Wenn kein Moment
auf die Strömung.

Prof. Dr.-Ing. Peter Pelz
Wintersemester 2012/13
Vorlesung 11 F 143



$$\text{Totale Enthalpie} = \frac{\text{Druck}}{\text{Dichte}} + \frac{c_{\text{rel}}^2}{2} + \text{innere Energie} + \text{Pot. en.}$$

$$= \frac{p}{\rho} + \frac{c^2}{2} + e + \psi$$

$$h_{t2} - h_{t1} = \left[\frac{p}{\rho} + \frac{c^2}{2} + \psi \right]_2 - \left[\frac{p}{\rho} + \frac{c^2}{2} + \psi \right]_1 + (e_2 - e_1)$$

G_2

-

$G_1 := \rho g H$

$H > 0$ Arbeit

$H < 0$ Kamm.

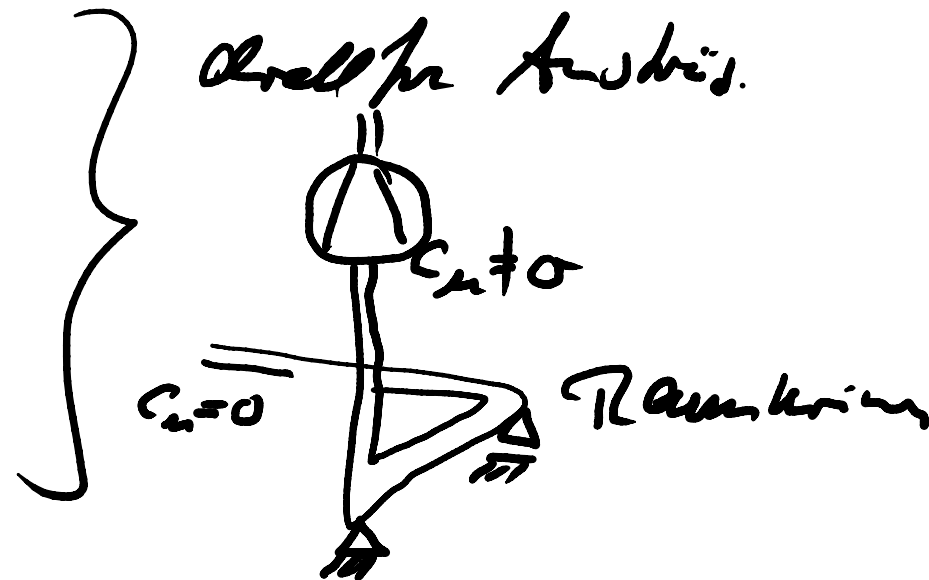
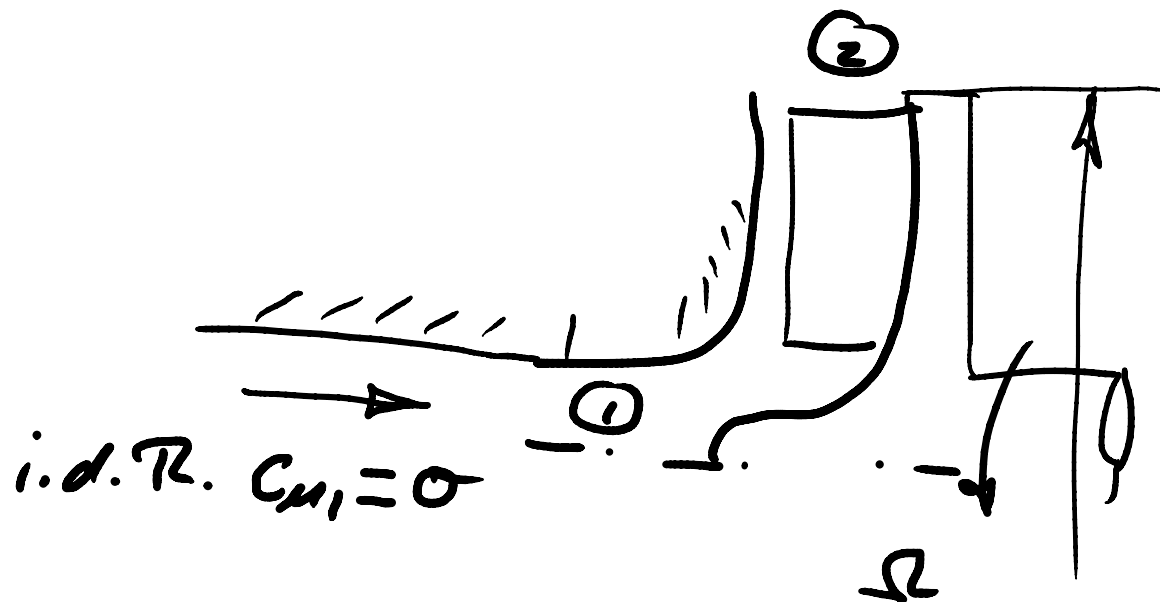
Förderhöhe oder

Fallhöhe.

C Bernoulli Konstante



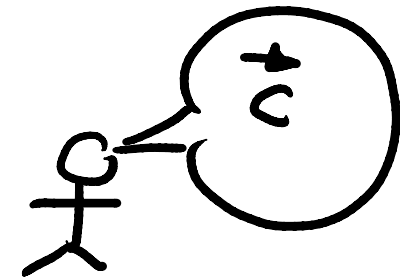
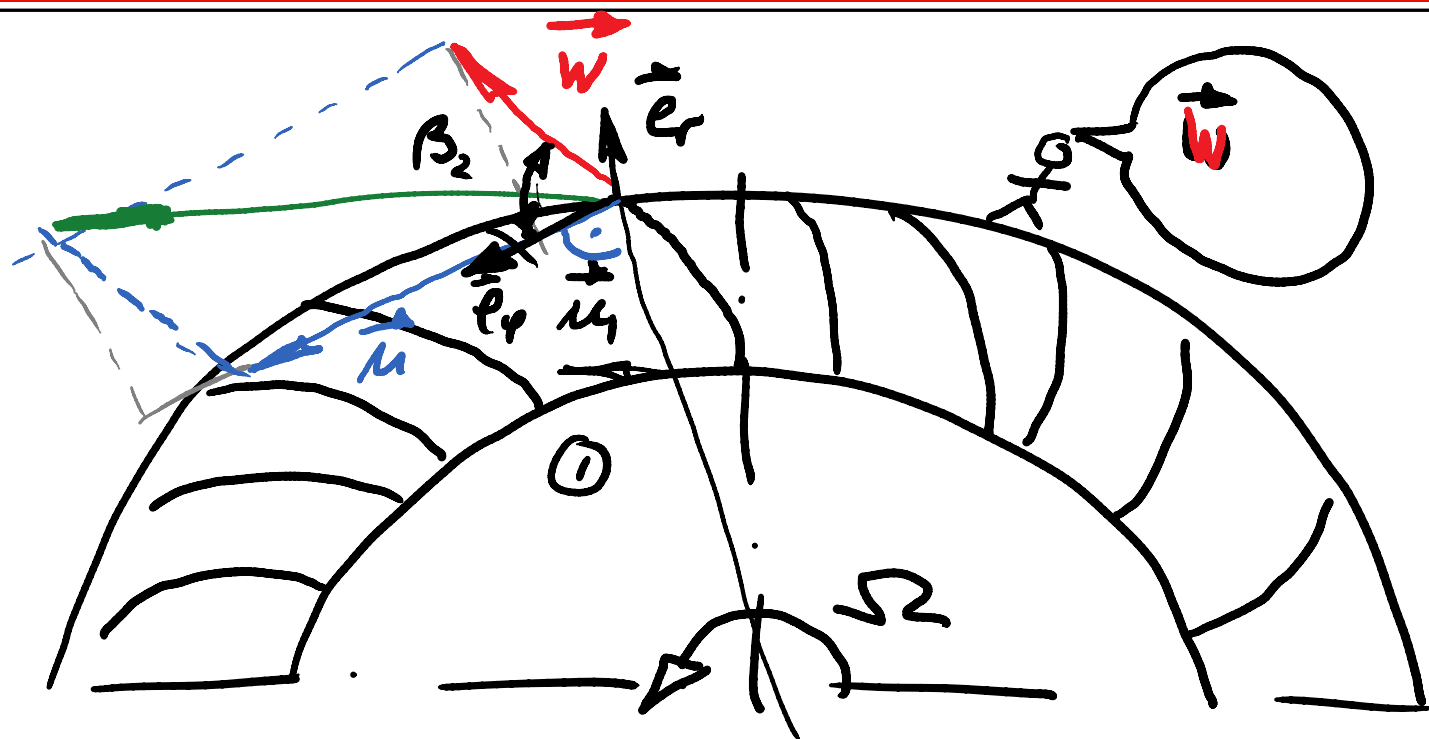
$$gH + (e_2 - e_1) = \mu_2 c_{u2} - \mu_1 c_{u1} \quad \Bigg| \quad \frac{1}{\mu_2}$$



drehen Antrieb.

$$\frac{gH}{\mu_2} + \frac{e_2 - e_1}{\mu_2} = \frac{c_{u2}}{\mu_2} - \frac{\tau_1}{\tau_2} \frac{c_{u1}}{\mu_2} = \frac{c_{u2}}{\mu_2} \quad \text{für drehen fest.}$$

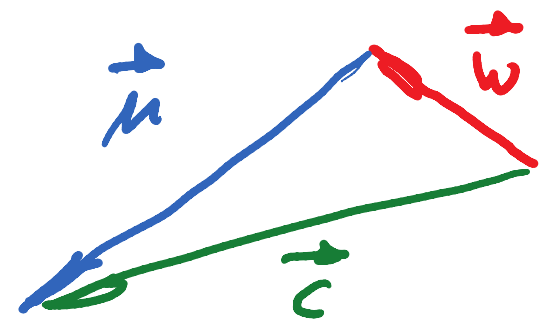
Ψ Drehziff. Ψ_v Verlust an Drehleistung durch
164 v c Pw b



$$\vec{u} = r \Omega \vec{e}_\varphi$$

$$\vec{c} = \vec{w} + \vec{u} \quad (+ \vec{u})$$

rel. Gesch. phys. Taylorgesch.



Peripheriegesch.

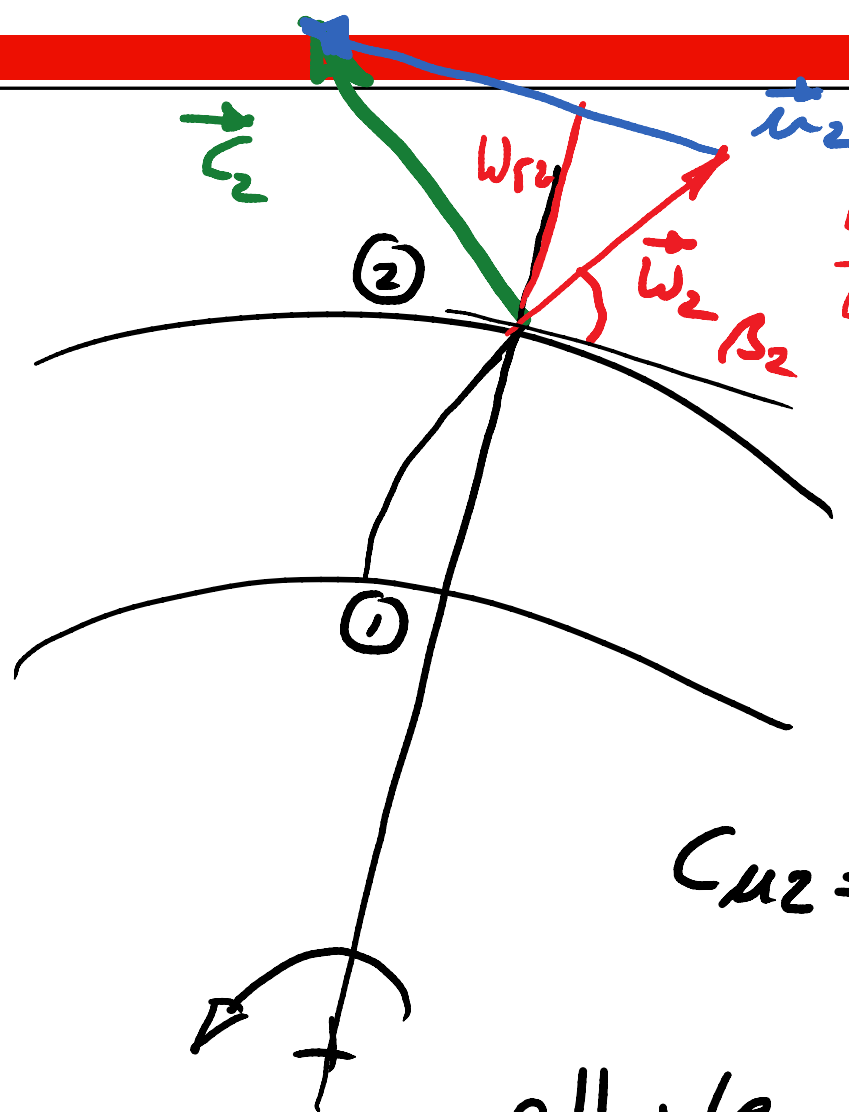
$$c_u = \Omega r_2 + w_{r_2} \cot \beta_2$$



▽

$$C_r = - \frac{Q}{2\pi r h}$$

4



$$\frac{w_{u2}}{w_{r2}} = \tan \beta_2$$

$$c_{u2} = \Omega r_2 - c_f \beta_2 u_{r2}$$

$$gH + (e_2 - e_1) = (\Omega r_2)^2 - c_f \beta_2 \frac{Q \Omega r_2}{2\pi r_2 b}$$

$$gH = \sum^{\pm 1} \left((\Omega r_2)^2 - c_f \beta_2 \frac{Q \Omega r_2}{2\pi r_2 b} \right)$$

Ω aerodynamisch, isentrop v. Uirly, rec

$\beta_1 = \beta_2$



Spezialfall

$$\rho_1 = \rho_2 = \rho$$

homogene Mittelbe

statist. dr. / Piezometrisch dr.

$$\rho g H = \Delta P_z = \left(P_2 + \rho \frac{c_2^2}{2} + \rho g z_2 \right) - \left(P_1 - \rho \frac{c_1^2}{2} + \rho g z_1 \right)$$

Durchfl.

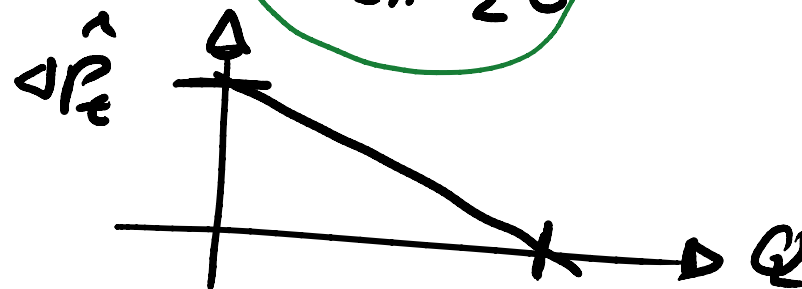
ψ

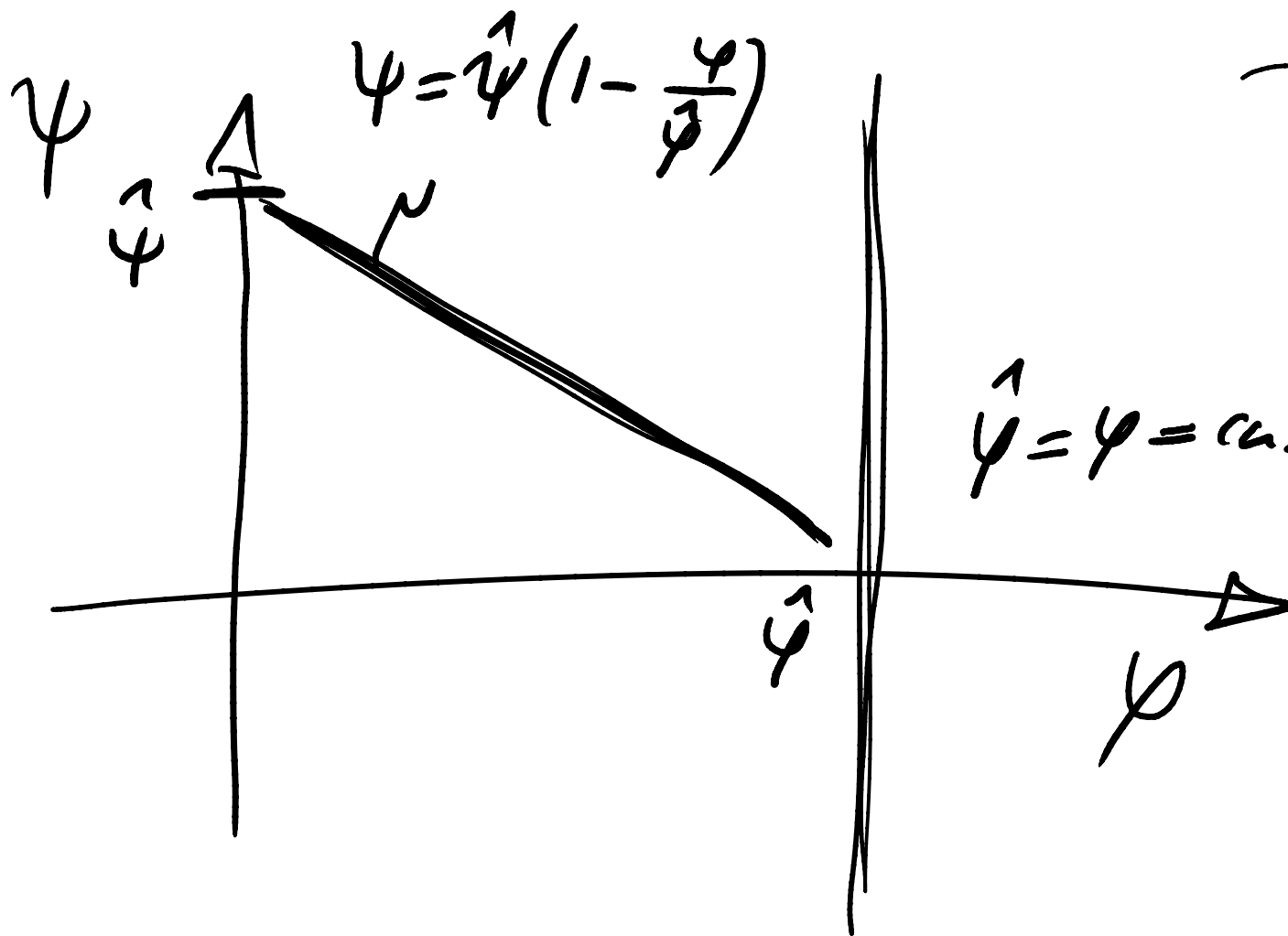
Total dr.

ψ Durchfl.

$$\Delta P_z = \sum^{\pm 1} \left(\rho \mu_2^2 - \rho \mu_2 \frac{Q}{2\pi r_2 b} \cdot \text{ctg}(\beta_2) \right) \left| \frac{1}{\mu_2^2} \right.$$

$$\Delta P_z \sim \rho \mu_2^2$$





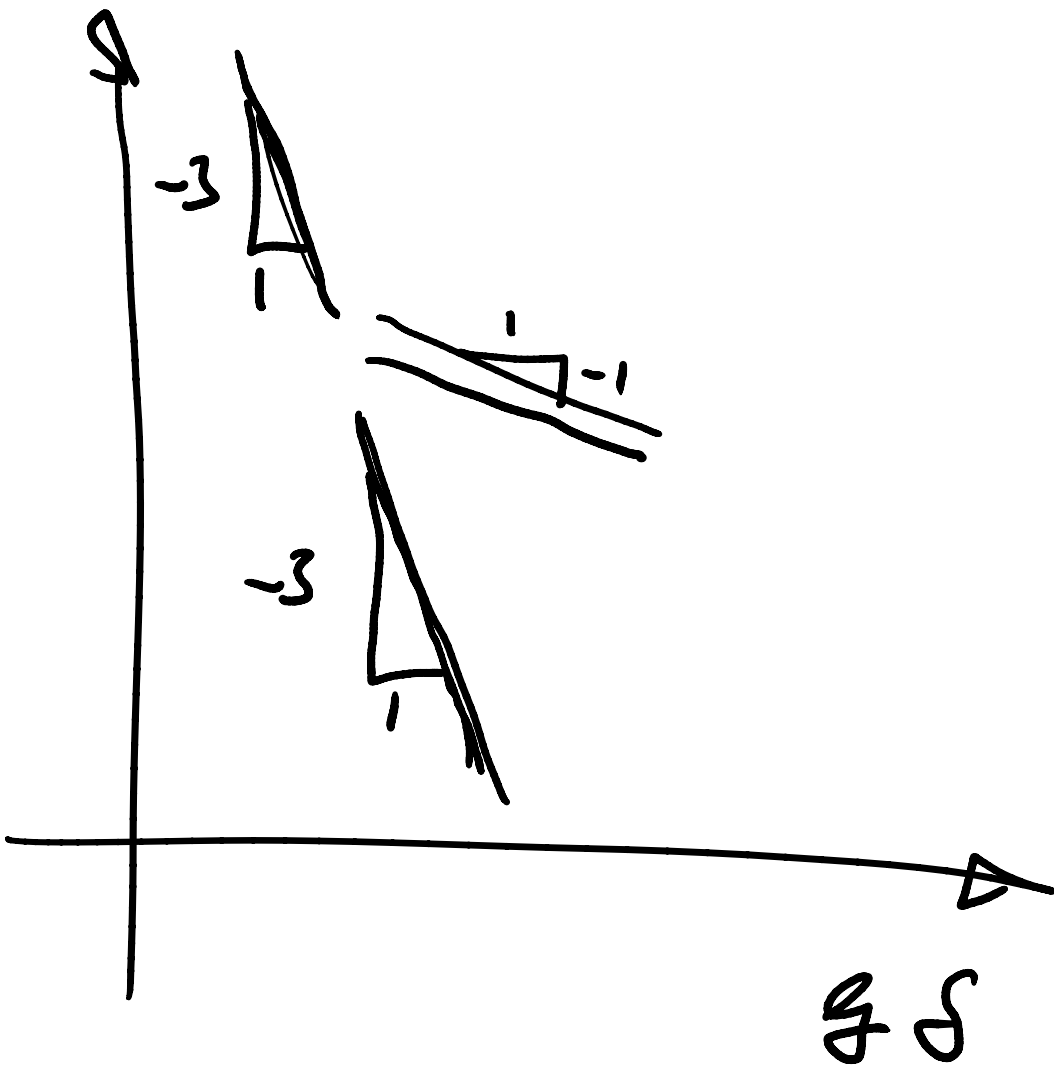
Transformierte



$$(\psi, \varphi) \rightarrow (\bar{\sigma}, \bar{\delta})$$

Cardan-
diagramm.

lg 6



TECHNISCHE
UNIVERSITÄT
DARMSTADT



Technische
Fluidsysteme

Prof. Dr.-Ing. Peter Pelz
Wintersemester 2012/13
Vorlesung 11 F 151